h2.0

The Next Best Thing to Really Being There:

Increasing the Emotional Bandwidth of Mediated Communication Using Robotic Avatars

Cynthia Breazeal

Human Communication When We Are Together



- Non-verbal cues are important indicators of states of mind and play an important role in coordinating minds
 - o Bodies do not have to be human

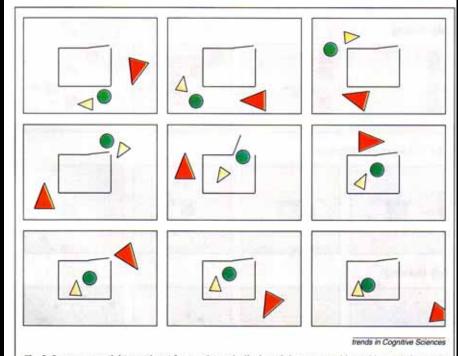


Fig. 3. Some sequential 'snapshots' from a dynamic display of the type used by Heider and Simme to demonstrate perceptual animacy⁹. Observers perceive the items in such displays as being alive, and even as having goals and intentional states such as desires (e.g. the large triangle might be seen as wanting to catch the small triangle).

Heider & Simme

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 - o Presents an interesting design space for robots

OperaBots May 8th, 2007

Robotic Life Group (Mikey Siegel & Jeff Lieberman) in collaboration with Opera of the Future

- Non-verbal cues are important indicators of states of mind and play an important role in coordinating minds
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 - o Presents an interesting design space for robots
 - o Or everyday artifacts with robotic technologies

2004 iMac G4 commercial

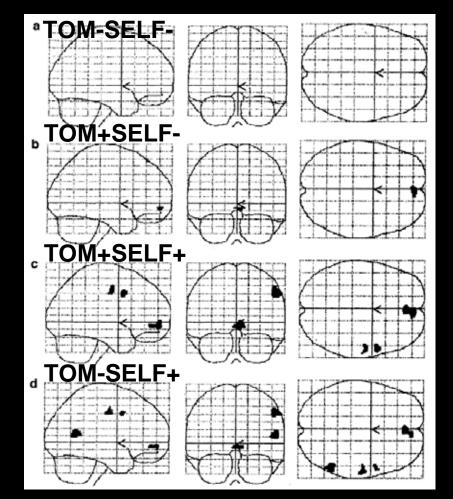
- Non-verbal cues are important indicators of states of mind and play an important role in coordinating minds
 - o Bodies do not have to be human
 - o Presents an interesting design space for robots
 - o Or everyday artifacts with robotic technologies
- The same "animate" artifacts can understand our intention through our non-verbal cues



AUR: A Robotic Desk Lamp (Guy Hoffman)

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- Simulation Theory: certain parts of the brain have dual use - they are used to not only generate behavior and mental states but also to predict and infer the same in others

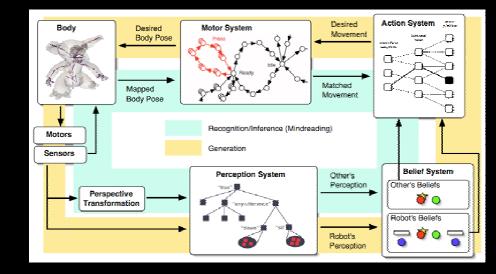


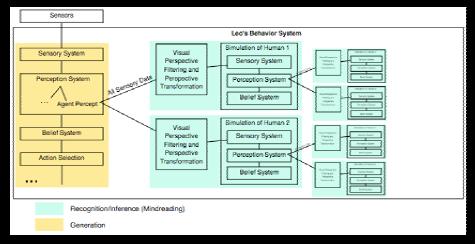
Vogeley et al, Neuro Image 14, 170-181 (2001)

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"I think that you think... That I think..."





Perspective Taking & False Belief Task



 Use own belief maintenance mechanisms to model and relate beliefs of others to its own beliefs

Multiple People, False Beliefs and Goal Inference for Collaboration

	Correct	Guidance	Grounding			Incorrect
lask	Object	Gesture	Gesture	Other	No Action	Object
Task 1	16	0	0	1†	1	2
lask 2	14	1	2	0	0	3
	10		<u> </u>	0	0	
'lask 4a	14	2	1	0	3	0
lask 4b	13	0	1	1 [‡]	1	4
+ One participant produced the object only after the key had been retrieved from box C.						
† Participant successfully pried open the locked target box.						

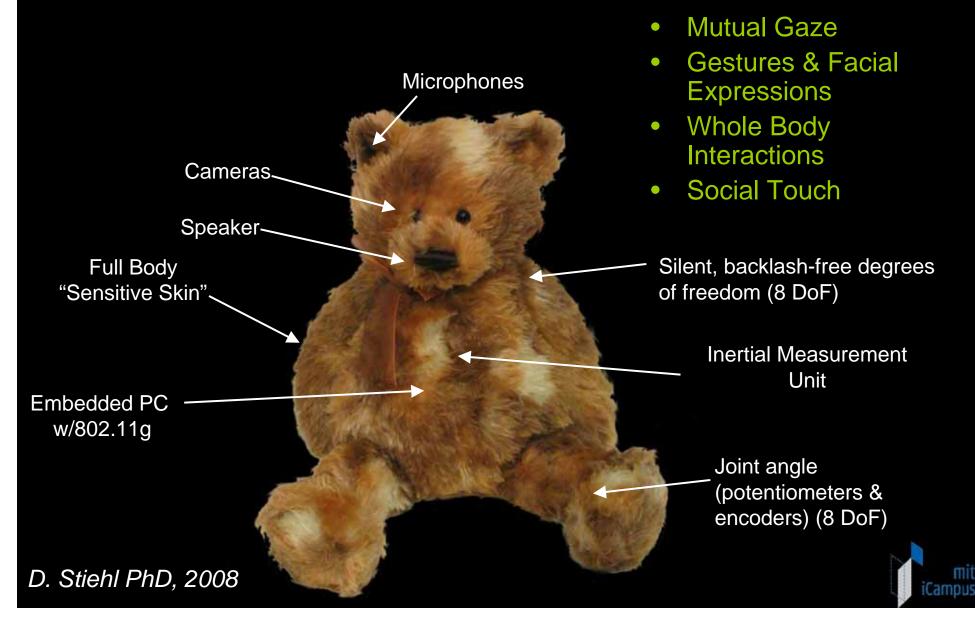
‡ Participant discovered the combination lock code and revealed it gesturally.

Performance on same task with 20 Human Subjects

Coordinating Minds and Bodies with Robots

- ✓ Robots that can exhibit non-verbal cues to help people attribute mind & coordinate their mind with it.
- Robots that perceive & interpret these non-verbal cues to coordinate their "mind" & behavior with people (collaborative machines)
- Robots that enable people to interact with others remotely using these same cues

The Huggable

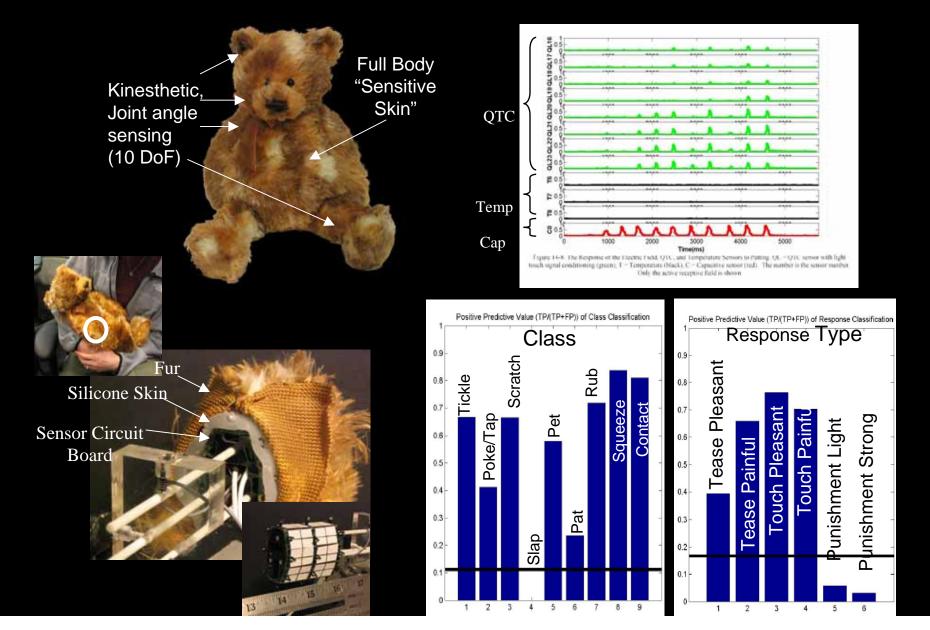


Whole Body Interaction

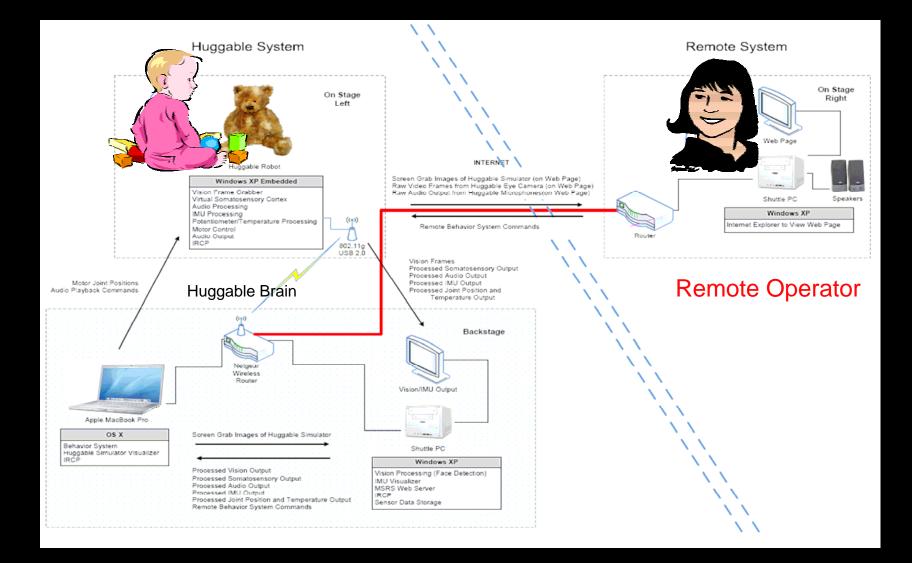
- One that can perceive these non-verbal cues
- One that can actively participate with people using these same cues face-to-face
- One that enables a human to interact with others remotely using these same cues



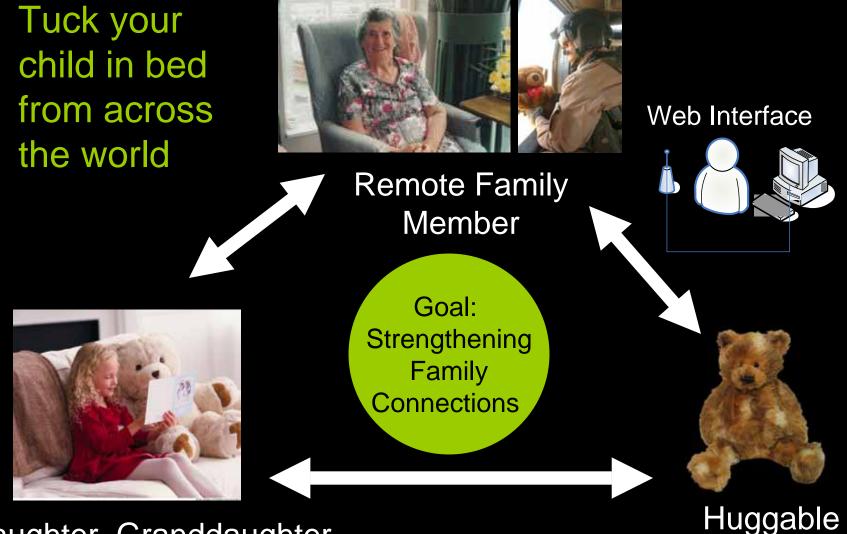
Social-Affective Touch



Communication Avatar Demo



Imagine: Playing with Family from Anywhere



Daughter, Granddaughter



Zoe and Olivia Hockenberry

First Impressions...

Imagine: Improving Experience in Hospitals

Your Child's first night alone at the **Hospital** Nurses Station Parents@Home Nurses 1.) Collected Data 2.) Distress Signal 3.) Live Video Feed 4.) Live Audio Feed 5.) Live Sensor Feed Goal: Improve **Experience** of Child & Family Child in Hospital Huggable

Imagine: Empowering Care Providers

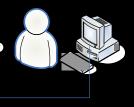
Provide Benefit of Pet Therapy and Tool for Nursing Staff



Hospital/Nursing

Home Staff

1.) Collected Data 2.) Distress Signal 3.) Live Video Feed 4.) Live Audio Feed 5.) Live Sensor Feed



Nurses Station



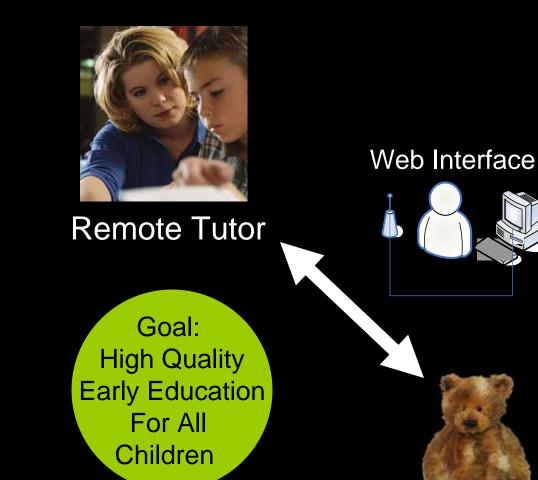
Resident/Patient

Goal: Promote Health and QoL of Person

Huggable

Imagine: A Private Tutor for Every Child

High Quality Early Education for Disadvantaged Children





Toddler/Child

Huggable

Thank You!

Grad Students and Postdocs

- Dan Stiehl
- Mikey Siegel
- Jeff Lieberman
- Matt Berlin
- Jesse Gray
- Guy Hoffman
- Dr. Andrea L. Thomaz

The Huggable UROP Army

- Robert Toscano
- Allan Maymin
- Dave Foster
- Yingdan Gu
- Iris Cheung Lily Liu
- Dimitrios Poulopoulos
- Yi Wang
- Nicolina Akraboff
- Kristopher Dos Santos